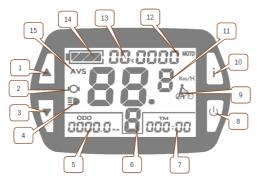
KT-LCD10YN E-Bike Display User Manual

Dear customer, please read this manual before you use KT-LCD10YN Display. The manual will guide you use the

instrument correctly to achieve a variety of vehicle control and vehicle status displays.

Functions and Display

Instruments using the structure form of instrument body portion and the operation buttons are designed separately.



1	$\mathbf{\Delta}$	UP Button	9	Â	6Km/H push power assist
2	Q	The brake display	10	i	Information Button
3		DOWN Button	11	Km/H	Riding speed(metric)
4		Backlight and headlights	12	MOT	Power display
5	DST	Trip distance	13	ĉ	Environment temperature
	ODO	Total distance		Ŧ	Environment fahrenheit
6	ASSIST	Pas level	14		Battery capacity indicator
7	TIM	Single trip time	15	AVS	Average speed
	TTM	Total trip time		MXS	MAX speed
8		SW Button			

Operation

1. ON/OFF

Hold witton long to turn on the power, and hold in long for a second time to turn off the power. When the motor stops driving and when the e-bike is not used for a consecutive 5 minutes, it will automatically shut down and turn off the motor power supply.



Display1 2.

Hold button to start up and enter display.

2.1 Turn on backlight and headlights

2.2 Assist ratio gear (ASSIST) switch

Hold **L** long to turn on backlight and headlights (the controller should have headlight drive output function); hold Iong again to turn off the backlight and headlights.

Press **D** or **D** to switch 1-5 file gear. Gear 1 is for the minimum power, gear 5 is for the highest power. Each startup

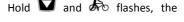
will automatically restore the gear shutdown last time (the user can set randomly). Gear 0 is without booster function.



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2.3 6Km/H assist promotion function

Hold \blacksquare and \bigstar flashes, the vehicle drives at the speed not more than 6Km /h. Release 🔽 button, the function is invalid.

2.4 Display and delete of single data

After power on for 5 seconds, hold **A** and **A** at the same time, single trip riding time (TM) and single trip distance (DST) flash, hold **i** button shortly, the content of both is cleared. If failed holding the button within 5 seconds, it will automatically return the display interface after 5 seconds, original content is preserved.

3. Display2

Hold **i** button shortly in display 1 to enter display 2. In the riding mode after 5 seconds, display 2 automatically returns to display 1, and the original motor power (MOTOR W) display the output of temperature detection signal).



4. Display 3

Hold **i** button shortly in display 2 to enter display 3.

In the riding condition, five seconds later, a single

maximum speed (MXS) display automatically returns to the real riding speed (Km/H).

5. In display 3, hold **i** button shortly, and the display will

re-enter display 1.

- 6. Hold 🔟 button to turn off the display and the power supply of controller.
- 7. Automatically prompt interface
- 7.1 Error Code Display
 - 1. Motor position sensor fault!
 - 2. THROTTLE fault!
 - 3. Motor or controller short circuit fault!

Electronic control system failure will display (flashing) fault code. Once the fault was removed, it automatically exits from the fault code display interface.

7.2 Motor temperature alarm When the motor temperature (the internal motor should be equipped with the temperature sensor and the output of temperature detection signal) is over the warning value, MOTOR °C (°F) flashes to alarm at any display, meanwhile the motor controller will offer the appropriate protection to motor.

General Project Setting

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1. Set maximum riding speed

Within power on 5 seconds, hold \square and \square at the same time to enter maximum riding speed Km/H and MXS setting, press i button maximum riding speed flashing, then press \square or \square to set the maximum riding speed (default 25Km/H). Press i button to save the setting, and press \square to the next parameter settings.

2. Wheel diameter setting

The wheel diameter will be set after finishing setting the maximum riding speed, press **i** button wheel diameter specifications flashes. Press or to set the specifications of wheel diameter. Select the range 6,8,10,12,14,16,18,20,22,24,26,700c,28and 29 inches.



Press i button to save and press v to go to the next parameter settings.

3. Set the metric units

The metric units will be set after finishing setting wheel diameter, press **i** button UNT flash. Press **o** or **v** to select the three metric units of speed, mileage, and ambient temperature in synchronization.

Code	Speed	Mileage	Ambient temperature
0	Km/H	Km	$^{\circ}\mathrm{C}$ (Centigrade temperature)
1	MPH	Mil	$^{\circ}\mathrm{C}$ (Centigrade temperature)
2	Km/H	Km	$^{\circ}\!\mathrm{F}$ (Fahrenheit)
3	MPH	Mil	$^{\circ}\!\mathrm{F}$ (Fahrenheit)

4. Press **i** button UNT stop flash after metric unit setting is completed. Hold **i** button long to exit from setting environment of routine projects and save the setting values, returning to display

5. Exit from routine project setting

All three routine project settings can exit from the setting environment and return to the display by holding **i** button long after each setting is completed, meanwhile the setting values are saved.

Under each setting interface, if the button failed holding for more than 1 minute, it will automatically return to display 1, and the setting value is invalid.

Outline Drawings and Dimensions

1. Dimensions of main instrument body

3. Wiring diagram



